



Alexandria University

Faculty of Engineering

Electrical Engineering Department

CS x35: Computer Architectures
Course Design Project

Overview:

In this projects you will implement a subset of the pipelined MIPS architecture in HDL. You will implement a functioning outline of the pipelined processor for a small set of instructions, including: decoding all the instructions you will encounter in this project, implementing most of the MIPS pipeline, correct implementation of arithmetic and logic operations, and implementing a hazard detection and avoidance unit for these instructions.

Academic Integrity. As one of the most widely studied architectures, MIPS has a wealth of information available on the web and in textbooks. You may consult any MIPS documentation available to you in order to learn about the instruction set, what each instruction does, etc. But we expect your design to be entirely your own, and your submission should cite any significant sources of information you used. Plagiarism in any form will not be tolerated. It is also your responsibility to make sure your sources match the material we describe here (warning: the top Google hit for "MIPS reference" contains several inaccuracies).

Requirements:

You will implement a five-stage MIPS pipeline, which is the most common organization for MIPS and is similar to what is described in the book and in class:

1. Fetch
2. Decode
3. Execute
4. Memory
5. Writeback

Your design should contain a program counter, a separate data and code memories, a register file, an ALU, and any other components needed, along with the instruction decode and control circuits and a hazard unit. The pipeline should: fetch instructions to execute from the code memory and increment the program counter by 4; decode each instruction; select arguments from the register file; compute results; do nothing in the memory stage; and store results back in the register file. Your processor must correctly execute all of the highlighted instructions in Table 1.

Table 1: MIPS Instruction Set

| Opcodes | Example Assembly | Semantics |
|-----------------------------------|----------------------------|---|
| add | add \$1, \$2, \$3 | \$1 = \$2 + \$3 |
| sub | sub \$1, \$2, \$3 | \$1 = \$2 - \$3 |
| add immediate | addi \$1, \$2, 100 | \$1 = \$2 + 100 |
| add unsigned | addu \$1, \$2, \$3 | \$1 = \$2 + \$3 |
| subtract unsigned | subu \$1, \$2, \$3 | \$1 = \$2 - \$3 |
| add imm. Unsigned | addiu \$1, \$2, 100 | \$1 = \$2 + 100 |
| multiply | mult \$2, \$3 | hi, lo = \$2 * \$3 |
| multiply unsigned | multu \$2, \$3 | hi, lo = \$2 * \$3 |
| divide | div \$2, \$3 | lo = \$2/\$3, hi = \$2 mod \$3 |
| divide unsigned | divu \$2, \$3 | lo = \$2/\$3, hi = \$2 mod \$3 |
| move from hi | mfhi \$1 | \$1 = hi |
| move from low | mflo \$1 | \$1 = lo |
| and | and \$1, \$2, \$3 | \$1 = \$2 & \$3 |
| or | or \$1, \$2, \$3 | \$1 = \$2 \$3 |
| and immediate | andi \$1, \$2, 100 | \$1 = \$2 & 100 |
| or immediate | ori \$1, \$2, 100 | \$1 = \$2 100 |
| shift left logical | sll \$1, \$2, 10 | \$1 = \$2 << 10 |
| shift right logical | srl \$1, \$2, 10 | \$1 = \$2 >> 10 |
| load word | lw \$1, \$2(100) | \$1 = ReadMem32(\$2 + 100) |
| store word | sw \$1, \$2(100) | WriteMem32(\$2 + 100, \$1) |
| load halfword | lh \$1, \$2(100) | \$1 = SignExt(ReadMem16(\$2 + 100)) |
| store halfword | sh \$1, \$2(100) | WriteMem16(\$2 + 100, \$1) |
| load byte | lb \$1, \$2(100) | \$1 = SignExt(ReadMem8(\$2 + 100)) |
| store byte | sb \$1, \$2(100) | WriteMem8(\$2 + 100, \$1) |
| load upper immediate | lui \$1, 100 | \$1 = 100 << 16 |
| branch on equal | beq \$1, \$2, Label | if (\$1 == \$2) goto Label |
| branch on not equal | bne \$1, \$2, Label | if (\$1 != \$2) goto Label |
| set on less than | slt \$1, \$2, \$3 | if (\$2 < \$3) \$1 = 1 else \$1 = 0 |
| set on less than immediate | slti \$1, \$2, 100 | if (\$2 < 100) \$1 = 1 else \$1 = 0 |
| set on less than unsigned | sltu \$1, \$2, \$3 | if (\$2 < \$3) \$1 = 1 else \$1 = 0 |
| set on less than immediate | sltui \$1, \$2, 100 | if (\$2 < 100) \$1 = 1 else \$1 = 0 |
| jump | j Label | goto Label |
| jump register | jr \$31 | goto \$31 |
| jump and link | jal Label | \$31 = PC + 4; goto Label |

Build your MIPS processor using your preferred HDL language and you can use any component implemented in the course textbook. The pipelined MIPS architecture and main components you should build in your design are shown in Figure 1. In this project, the instruction and data memories are separated from the main processor and connected by address and data busses. You only need to modify the processor architecture to support the highlighted instructions given in Table 1.

Testing

Write a test program in MIPS assembly that fully tests all of the features you have implemented. Our testing programs for this project will include a mixture of instructions from Table 1. This is a critical step, and you will use the MIPS testbench given by the textbook and shown in this section. The MIPS testbench loads a program into the memories. The program in Figure 3 exercises some of the instructions by performing a computation that should produce the correct answer only if all of the instructions are functioning properly. Specifically, the program will write the value 7 to address 84 if it runs correctly, and is unlikely to do so if the hardware is buggy. This is an example of ad hoc testing. The machine code is stored in a hexadecimal file called memfile.dat, which is loaded by the testbench during simulation. The file consists of the machine code for the instructions, one instruction per line.

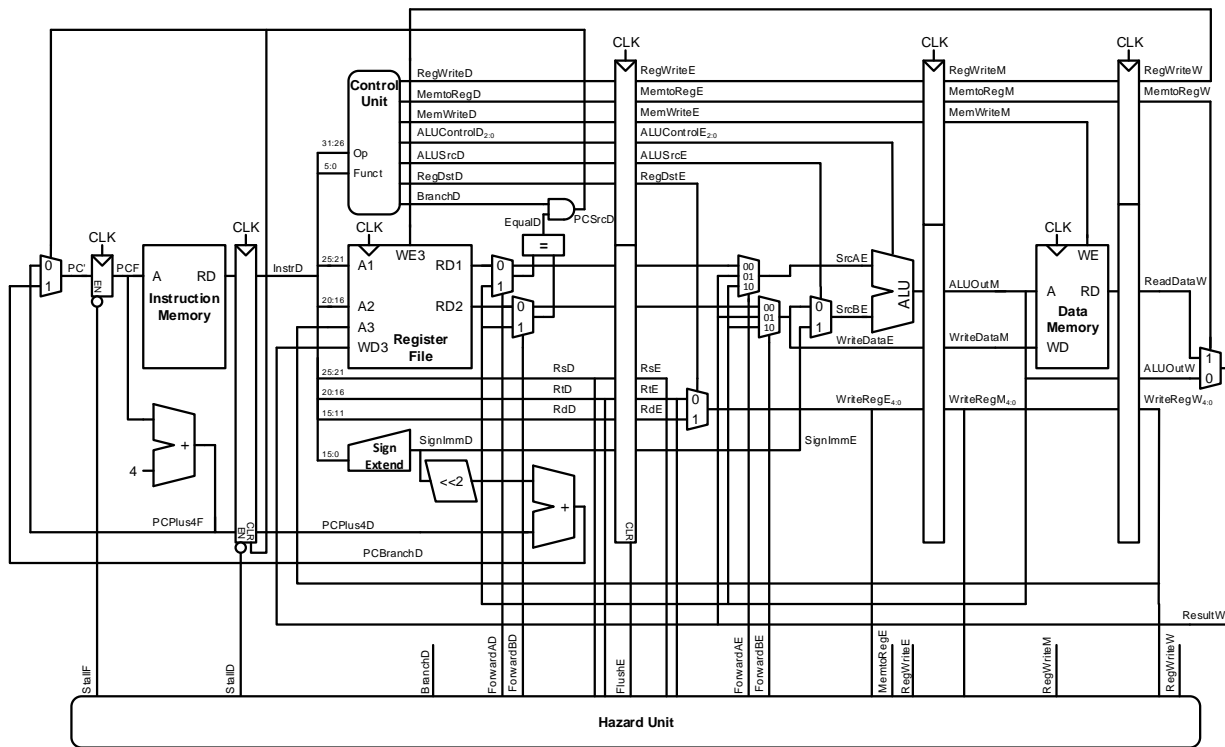


Figure 1: Pipelined MIPS Processor

Documentation

The design document should include a block diagram showing all the major changes in the given architecture. You need not completely draw wires for control logic signals, but should indicate which components take control inputs, and give names to all control signals. Also include a description of your control and instruction decoding logic. For each control logic signal (or group of related control logic signals) you should provide (a) a brief description of what the signal does, e.g. what the values of the control signal

mean; and (b) a truth table showing what value the signal takes for each possible opcode.

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# mipstest.asm
# David_Harris@hmc.edu, Sarah_Harris@hmc.edu 31 March 2012
#
# Test the MIPS processor.
# add, sub, and, or, slt, addi, lw, sw, beq, j
# If successful, it should write the value 7 to address 84

#      Assembly      Description      Address      Machine
main:  addi $2, $0, 5      # initialize $2 = 5      0      20020005      20020005
      addi $3, $0, 12   # initialize $3 = 12     4      2003000c      2003000c
      addi $7, $3, -9   # initialize $7 = 3      8      2067ffff7     2067ffff7
      or  $4, $7, $2    # $4 = (3 OR 5) = 7     c      00e22025     00e22025
      and $5, $3, $4    # $5 = (12 AND 7) = 4   10     00642824     00642824
      add $5, $5, $4    # $5 = 4 + 7 = 11      14     00a42820     00a42820
      beq $5, $7, end   # shouldn't be taken    18     10a7000a     10a7000a
      slt $4, $3, $4    # $4 = 12 < 7 = 0     1c     0064202a     0064202a
      beq $4, $0, around # should be taken      20     10800001     10800001
      addi $5, $0, 0    # shouldn't happen     24     20050000     20050000
around: slt $4, $7, $2    # $4 = 3 < 5 = 1      28     00e2202a     00e2202a
      add $7, $4, $5    # $7 = 1 + 11 = 12     2c     00853820     00853820
      sub $7, $7, $2    # $7 = 12 - 5 = 7     30     00e23822     00e23822
      sw  $7, 68($3)    # [80] = 7             34     ac670044     ac670044
      lw  $2, 80($0)    # $2 = [80] = 7       38     8c020050     8c020050
      j   end          # should be taken      3c     08000011     08000011
      addi $2, $0, 1    # shouldn't happen     40     20020001     20020001
end:    sw  $2, 84($0)    # write mem[84] = 7   44     ac020054     ac020054

```

Figure 2: Assembly and machine code for MIPS test program